# Topological Manin pairs and ( $n, s$ )-type series 

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#### Abstract

Lie subalgebras of $L=\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]$, complementary to the diagonal embedding $\Delta$ of $\mathfrak{g} \llbracket x \rrbracket$ and Lagrangian with respect to some particular form, are in bijection with formal classical $r$-matrices and topological Lie bialgebra structures on the Lie algebra of formal power series $\mathfrak{g} \llbracket x \rrbracket$. In this work we consider arbitrary subspaces of $L$ complementary to $\Delta$ and associate them with so-called series of type $(n, s)$.

We prove that Lagrangian subspaces are in bijection with skew-symmetric ( $n, s$ )-type series and topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$. Using the classificaiton of Manin pairs we classify up to twisting and coordinate transformations all quasi-Lie bialgebra structures.

Series of type ( $n, s$ ), solving the generalized classical Yang-Baxter equation, correspond to subalgebras of $L$. We discuss their possible utility in the theory of integrable systems.


Dedicated to the memory of Yuri Manin

## 1 Introduction

Let $F$ be an algebraically closed field of characteristic 0 equipped with the discrete topology and $\mathfrak{g}$ be a simple Lie algebra over $F$. We define the Lie algebra $\mathfrak{g} \llbracket x \rrbracket$ to be the space $\mathfrak{g} \otimes F \llbracket x \rrbracket$ with the bracket

$$
[a \otimes f, b \otimes g]=[a, b] \otimes f g
$$

and we equip it with the ( $x$ )-adic topology. The continuous dual of $\mathfrak{g} \llbracket x \rrbracket$ is denoted by $\mathfrak{g} \llbracket x \rrbracket^{\prime}$ and it is endowed with the discrete topology.

A topological Manin pair is a pair $(L, \mathfrak{g} \llbracket x \rrbracket)$ where

1. $L$ is a Lie algebra equipped with an invariant non-degenerate symmetric bilinear form $B$;
2. $\mathfrak{g} \llbracket x \rrbracket \subset L$ is a Lagrangian subalgebra with respect to $B$;
3. for any continuous functional $T: \mathfrak{g} \llbracket x \rrbracket \rightarrow F$ there is $f \in L$ such that $T=B(f,-)$.

Topological Manin pairs were classified in 1$]$ using the tools from 8 . More precisely, if ( $L, \mathfrak{g} \llbracket x \rrbracket$ ) is a topological Manin pair, then $L$ is isomorphic, as a Lie algebra with form, to either $L(\infty)$ or $L(n, \alpha)$. In this paper we consider only the "non-degenerate" case, namely $L \cong L(n, \alpha)$.

As a Lie algebra

$$
L(n, \alpha)=\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x] .
$$

The bilinear form $B$ on $L(n, \alpha)$ is completely determined by the sequence $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$. For example, when $n=0$ the form is given by

$$
B(a \otimes f, b \otimes g)=\kappa(a, b) \operatorname{res}_{0}\{\alpha(x) f g\}
$$

where $\kappa$ is the Killing form on $\mathfrak{g}$ and $\alpha(x):=1+\alpha_{-2} x+\alpha_{-3} x^{2}+\cdots \in F((x))$. In case $n>0$ the form is given by a similar formula; see Section 2 .

It was established in 1], that the following objects are in one-to-one correspondence

[^0]- Lagrangian subalgebras $W \subseteq L(n, 0), 0 \leqslant n \leqslant 2$, complementary to the diagonal

$$
\Delta:=\{(f,[f]) \mid f \in \mathfrak{g} \llbracket x \rrbracket\},
$$

i.e. $\Delta \dot{+} W=L(n, 0)$;

- non-degenerate topological Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$ and
- formal solutions to the classical Yang-Baxter equation (CYBE) in the form

$$
\begin{equation*}
\frac{y^{n} \Omega}{x-y}+g(x, y)=\Omega \sum_{k \geqslant 0} x^{-k-1} y^{k+n}+g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket \tag{1}
\end{equation*}
$$

where $\Omega \in \mathfrak{g} \otimes \mathfrak{g}$ is the quadratic Casimir element and $g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$.
Furthermore, the proof of the above-mentioned correspondence reveals that series Eq. (1) can be viewed as a generating series for the corresponding subalgebra $W$. The present paper can be thus considered as a continuation of [1], where we extend the preceding correspondence using series of type ( $n, s$ ).

To define a series of type $(n, s)$ fix a basis $\left\{b_{i}\right\}_{i=1}^{d}$ of $\mathfrak{g}$, orthonormal with respect to its Killing form $\kappa$, and interpret $y^{n} \Omega /(x-y)$ as a series

$$
\begin{equation*}
\frac{y^{n} \Omega}{x-y}=\sum_{k=0}^{\infty} \sum_{i=1}^{d} w_{k, i} \otimes b_{i} y^{k} \in\left(\left(\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]\right) \otimes \mathfrak{g}\right) \llbracket y \rrbracket . \tag{2}
\end{equation*}
$$

This expression might be understood as a Taylor series expansion. Elements $w_{k, i} \in \mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]$ are presented explicitly in Eq. (19). A series of type $(n, s)$ is a series of the form

$$
\begin{equation*}
\frac{s(x) y^{n} \Omega}{x-y}+g(x, y) \in\left(\left(\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]\right) \otimes \mathfrak{g}\right) \llbracket y \rrbracket \tag{3}
\end{equation*}
$$

where $s \in F \llbracket x \rrbracket^{\times}$and $g \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$; See Definition 3.2. For each series $r$ of type $(n, s)$ we define another series $\bar{r}$ of the same type as follows

$$
\begin{equation*}
\bar{r}:=\frac{s(y) x^{n} \Omega}{x-y}-\tau(g(y, x)) \tag{4}
\end{equation*}
$$

where $\tau$ is the $F \llbracket x, y \rrbracket$-linear extension of the map $a \otimes b \mapsto b \otimes a$.
Each series of type $(n, s)$ produces a subspace of $\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]$ complementary to the diagonal embedding $\Delta$ of $\mathfrak{g} \llbracket x \rrbracket$. The following results generalize the above-mentioned correspondence from [1].

Theorem A. Let $n \in \mathbb{Z}_{\geqslant 0}$ and $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ be an arbitrary sequence with the corresponding series $\alpha(x):=x^{-n}+\alpha_{n-2} x^{-n+1}+\cdots+\alpha_{0} x^{-1}+\cdots \in F((x))$. For any ( $\left.n, s\right)$-type series

$$
\begin{equation*}
r=\sum_{k=0}^{\infty} \sum_{i=1}^{d} f_{k, i} \otimes b_{i} y^{k} \in\left(\left(\mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]\right) \otimes \mathfrak{g}\right) \llbracket y \rrbracket \tag{5}
\end{equation*}
$$

define the space

$$
\begin{equation*}
W(r):=\operatorname{span}_{F}\left\{f_{k, i} \mid k \geqslant 0,1 \leqslant i \leqslant d\right\} \subseteq \mathfrak{g}((x)) \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x] \tag{6}
\end{equation*}
$$

The following results are true:

1. W defines a bijection between series of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ and subspaces $V \subset L(n, \alpha)$ complementary to the diagonal $\Delta$, i.e. $L(n, \alpha)=\Delta \dot{+} V$;
2. For any series $r$ of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ we have $W(r)^{\perp}=W(\bar{r})$ inside $L(n, \alpha)$;
3. Any series $r$ of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ satisfies $\operatorname{GCYB}(r)=\psi$ (see Definition 3.5 for the meaning of $\mathrm{GCYB}(r)$ ), where $\psi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket x_{1}, x_{2}, x_{3} \rrbracket$ is defined by

$$
B\left(v_{1} \otimes v_{2} \otimes v_{3}, \psi\right)=B\left(v_{1},\left[v_{2}, v_{3}\right]\right)
$$

for all $v_{1} \in W(\bar{r}), v_{2}, v_{3} \in W(r)$.
In particular, considering the case when $r$ is skew-symmetric, meaning $r=\bar{r}$, or when $\psi=0$ we get the following correspondences.

Corollary B. Let $n \in \mathbb{Z}_{\geqslant 0}$, $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ and $W$ be the map from Theorem $A$. Then

1. W defines a bijection between skew-symmtric $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$-type series and Lagrangian subspaces $V \subseteq L(n, \alpha)$, complementary to the diagonal $\Delta$;
2. $W$ defines a bijection between $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$-type series solving the $G C Y B E$ and subalgebras $V \subseteq L(n, \alpha)$ complementary to the diagonal $\Delta$.

Observe that an $(n, s)$-type series produces a subspace of $L(n, \alpha)$ for any sequence $\alpha$. However, to obtain the compatibility with the form, given by $\alpha$, we need the equality $s(x)=1 /\left(x^{n} \alpha(x)\right)$. In this case, the components $f_{k, i}$ and $b_{i} y^{k}$ of the series become dual bases for $W(r)$ and $\Delta$ respectively.

The requirement on a series $r$ of type $(n, s)$ to solve the CYBE is equivalent to being skew-symmetric and to solve the GCYBE. Together with Corollary B this implies that Lagrangian subalgebras $W \subset L(n, \alpha)$, satisfying $W \dot{+} \Delta=L(n, \alpha)$, are in bijection with $\left(n, 1 /\left(x^{n} \alpha(x)\right)\right)$-type series solving the classical Yang-Baxter equation. These correspondences are schematically depicted in Fig. 1.

$$
(n, s)-\text { type series }
$$

> Subspaces complementary to $\Delta$



Figure 1: Series-subspaces correspondence

Remark 1.1. Let $r$ be a series of type ( $n, s$ ). Applying the projection $(a, b) \otimes c \mapsto a \otimes c$ onto the left component to $r$ we obtain the series

$$
\begin{equation*}
r_{\mathrm{proj}}=\frac{s(x) y^{n} \Omega}{x-y}+g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket \tag{7}
\end{equation*}
$$

Conversely, starting with a series $r_{\text {proj }}$ of the form Eq. (7), we can obtain an ( $\left.n, s\right)$-type series $r$ by taking two Taylor series expansions of $r_{\text {proj }}$ at $x=0$ and $y=0$ respectively and then constructing $r$ by combining the coefficients of $b_{i} y^{k}, k \geqslant 0$, in these expansions. These two constructions are inverse to each other and hence both $r$ and its projection $r_{\text {proj }}$ contain exactly the same information. Consequently, all the statements made for $(n, s)$-type series can be stated in terms of their projections onto the left component and vice versa. In cotrast with [1], in this paper we give preference to series of type $(n, s)$ rather than to their projections, because the statement that series of type $(n, s)$ generate subspaces of $L(n, \alpha)$ becomes transparent.

Reinterpreting the results of [1] in terms of $(n, s)$-type series we see that skew-symmetric series of type $\left(n, 1 /\left(x^{n} \alpha(x)\right)\right.$, that also solve the GCYBE, exist only for $n=0,1$ and $n=2$ with $\alpha_{0}=0$.

Lagrangian subalgebras of $L(n, \alpha)$, complementary to $\Delta$, correspond to topological Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$. If we instead consider Lagrangian subspaces (not necessarily subalgebras) of $L(n, \alpha)$, we get so called (non-degenerate) topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$. A topological quasi-Lie bialgebra structure on $\mathfrak{g} \llbracket x \rrbracket$ consists of

- a skew-symmetric continuous linear map $\delta: \mathfrak{g} \llbracket x \rrbracket \rightarrow(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ and
- a skew-symmetric element $\varphi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y, z \rrbracket$,
which are subject to the following three conditions

1. $\delta([a, b])=[a \otimes 1+1 \otimes a, \delta(b)]-[b \otimes 1+1 \otimes b, \delta(a)]$, i.e. $\delta$ is a 1-cocycle;
2. $\quad \frac{1}{2} \operatorname{Alt}((\delta \otimes 1) \delta(a))=[a \otimes 1 \otimes 1+1 \otimes a \otimes 1+1 \otimes 1 \otimes a, \varphi] ;$
3. $\operatorname{Alt}((\delta \otimes 1 \otimes 1) \varphi)=0$,
where $\operatorname{Alt}\left(x_{1} \otimes \ldots \otimes x_{n}\right):=\sum_{\sigma \in S_{n}} \operatorname{sgn}(\sigma) x_{\sigma(1)} \otimes \ldots \otimes x_{\sigma(n)}$.
Following [5] we prove the following direct relation between $\delta, \varphi$ and skew-symmetric ( $n, s$ )-type series $r$.
Proposition C. There is a bijection between topological quasi-Lie bialgebras and skew-symmetric ( $n, s)$-type series. Let $r$ be the $(n, s)$-type series corresponding to $(\mathfrak{g} \llbracket x \rrbracket, \delta, \varphi)$, then, under the identification $\mathfrak{g} \llbracket x \rrbracket \cong \Delta$, we have the following identities:

- $\quad[a \otimes 1+1 \otimes a, r]=-\delta(a)$ for any $a \in \mathfrak{g} \llbracket x \rrbracket$ and
- $\quad \mathrm{CYB}(r)=-\varphi$.

The same is true if $r$ is interpreted as an element in $(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket$.
In view of this result we call skew-symmetric $(n, s)$-type series quasi- $r$-matrices.
Repeating the ideas from [7] and [5] we show that topological quasi-Lie bialgebras can be twisted similar to topological Lie bialgebras. More precisely, if $\delta$ is a quasi-Lie bialgebra structure on $\mathfrak{g} \llbracket x \rrbracket$, given by the Lagrangian subspace $W$, and $s:=\sum_{i} a_{i} \otimes b^{i} \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ is an arbitrary skew-symmetric tensor, then

$$
\begin{equation*}
W_{s}:=\left\{\sum_{i} B\left(b^{i}, w\right) a_{i}-w \mid w \in W\right\} \tag{8}
\end{equation*}
$$

is another (twisted) Lagrangian subspace complementary to the diagonal. This observation implies, that in order to classify all topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket u p$ to twisting it is enough to find one single Lagrangian subspace within each $L(n, \alpha)$. Moreover, it was shown in 1 that substitutions of the form $x \mapsto x+a_{2} x^{2}+a_{3} x^{3}+\ldots, a_{i} \in F$, allow us to assume that $\alpha$ has the form

$$
\alpha=\left(\ldots, 0, \alpha_{0}, 0, \ldots, 0\right)
$$

Lagrangian subspaces for such $L(n, \alpha)$ are constructed in Section 4.1.
Using Theorem A and Proposition C we explain how twisting of a Lagrangian subspace $W \subset L(n, \alpha)$ is seen at the level of $\delta$ and the corresponding quasi- $r$-matrix $r$.

Corollary D. Let $(\mathfrak{g} \llbracket x \rrbracket, \delta, \varphi)$ be a topological quasi-Lie bialgebra structure corresponding to the quasi-r-matrix r. If we twist $W(r)$ with a skew-symmetric tensor s we obtain another topological quasi-Lie bialgebra ( $\mathfrak{g} \llbracket x \rrbracket, \delta_{s}, \varphi_{s}$ ), such that

1. $W(r)_{s}=W(r-s)$;
2. $\delta_{s}=\delta+d s$;
3. $\varphi_{s}=\varphi+\operatorname{CYB}(s)-\frac{1}{2} \operatorname{Alt}((\delta \otimes 1) s)$.

Therefore, to describe all quasi- $r$-matrices up to twisting it is enough to find one single quasi- $r$-matrix for each $L(n, \alpha)$. We achieve that goal in Section 4.2 by writing out explicitly series of type ( $n, s$ ) for subspaces from Section 4.1.

The results above, in particular, show that if $r$ is a quasi- $r$-matrix and $\delta(a):=[a \otimes 1+1 \otimes a, r]$, then the condition

$$
\begin{equation*}
\operatorname{Alt}((\delta \otimes 1 \otimes 1) \mathrm{CYB}(r))=0 \tag{9}
\end{equation*}
$$

is trivially satisfied.
We conclude the paper by using Theorem A for construction of Lie algebra splittings $\Delta \dot{+} W=L(n, \alpha)$ and the corresponding ( $n, s$ )-type series, which we call generalized $r$-matrices. These constructions are important in the theory of integrable systems because of their use in the Adler-Konstant-Symes (AKS) scheme and the so-called $r$-matrix approach; see [4. 6]. The subalgebra splittings of $L(0,0)$ as well as their physical applications were considered in e.g. 9, 10 .

Our first result shows that in order to obtain new generalized $r$-matrices from subalgebra splittings $L(n, \alpha)=$ $\Delta \dot{+} W$ with $n>2$, the subalgebra $W$ must be unbounded. Otherwise the situation can be reduced to the splitting of $L(2, \alpha)$.

Proposition E. Let $L(n, \alpha)=\Delta \dot{+} W$ for some subalgebra $W \subset L(n, \alpha)$ and $n>2$. Assume $W$ is bounded, i.e. there is an integer $N>0$ such that

$$
x^{-N} \mathfrak{g}\left[x^{-1}\right] \subseteq W_{+} \subseteq x^{N} \mathfrak{g}\left[x^{-1}\right]
$$

where $W_{+}$is the projection of $W \subset L(n, \alpha)=\mathfrak{g}((x)) \oplus \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]$ on the first component $\mathfrak{g}((x))$. Then we have the inclusion

$$
\{0\} \times\left[x^{2}\right] \mathfrak{g}[x] / x^{n} \mathfrak{g}[x] \subseteq W
$$

and the image $\widetilde{W}$ under the canonical projection $L(n, \alpha) \rightarrow L(2, \alpha)$ is a subalgebra satisfying $L(2, \alpha)=\Delta \dot{+} \widetilde{W}$.
Despite this result we think that bounded subalgebras $W \subset L(n, \alpha)$ complementary to $\Delta$ are still interesting, because in the case $\alpha \neq 0$ they lead to unbounded orthogonal complements $W^{\perp}$ which are also important in view of the AKS scheme. We give examples of subalgebras of $L(n, \alpha)$ with unbounded orthogonal complements.

## 2 Topological Manin pairs

Let $F$ be an algebraically closed field of characteristic $0, \mathfrak{g}$ be a finite-dimensional simple $F$-Lie algebra and $\mathfrak{g} \llbracket x \rrbracket:=\mathfrak{g} \otimes F \llbracket x \rrbracket$ be the Lie algebra with the bracket defined by

$$
[a \otimes f, b \otimes g]:=[a, b] \otimes f g
$$

for all $a, b \in \mathfrak{g}$ and $f, g \in F \llbracket x \rrbracket$. From now on, we always endow $F$ with the discrete topology and view $\mathfrak{g} \llbracket x \rrbracket$ as a topological Lie algebra with the $(x)$-adic topology.

A topological Manin pair is a pair $(L, \mathfrak{g} \llbracket x \rrbracket)$, where $L$ is a Lie algebra equipped with an invariant non-degenerate symmetric bilinear form $B$, such that

1. $\mathfrak{g} \llbracket x \rrbracket \subseteq L$ is a Lagrangian Lie subalgebra with respect to $B$;
2. for any continuous functional $T: \mathfrak{g} \llbracket x \rrbracket \rightarrow F$ there exists an element $f \in L$ such that $T=B(f,-)$.

The statements of [8, Proposition 2.9] and [1, Proposition 3.12] give a description of all topological Manin pairs. For precise formulation we need to repeat the definitions of some specific Lie algebras with forms from 1, Section 3.2] and [8, Section 2].
Definition 2.1. We define the Lie algebra $L(\infty):=\mathfrak{g} \otimes A(\infty)$, where $A(\infty)$ is the unital commutative algebra with underlying space $\sum_{i \geqslant 0} F a_{i}+F \llbracket x \rrbracket$ and multiplication given by

$$
a_{i} a_{j}:=0, a_{i} x^{j}:=a_{i-j} \text { for } i \geqslant j \text { and } a_{i} x^{j}:=0 \text { otherwise. }
$$

Let $\mathrm{t}: A \rightarrow F$ be the functional, given by $\mathrm{t}\left(a_{0}\right):=1, \mathrm{t}\left(a_{i}\right):=0, i \geqslant 1$ and $\mathrm{t}(F \llbracket x \rrbracket):=0$. We equip $L(\infty)$ with the symmetric non-degenerate invariant bilinear form

$$
\begin{equation*}
B\left(a \otimes\left(\sum_{i \geqslant 0} c_{i} a_{i}, f(x)\right), b \otimes\left(\sum_{i \geqslant 0} t_{i} a_{i}, g(x)\right)\right):=\kappa(a, b) \mathrm{t}\left(g(x) \sum_{i \geqslant 0} c_{i} a_{i}+f(x) \sum_{i \geqslant 0} t_{i} a_{i}\right) . \tag{10}
\end{equation*}
$$

Definition 2.2. Let $n \geqslant 1$ and $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ be an arbitrary sequence. Consider the algebra

$$
A(n, \alpha):=F((x)) \oplus F[x] /\left(x^{n}\right) .
$$

Abusing the notation we denote the element $x^{-n}+\alpha_{n-2} x^{-n+1}+\cdots+\alpha_{0} x^{-1}+\cdots \in F((x))$ with the same letter $\alpha$. Define the functional t: $A(n, \alpha) \rightarrow F$ by

$$
\mathrm{t}(f,[p]):=\operatorname{res}_{0}\{\alpha(f-p)\} .
$$

Taking the tensor product of $A(n, \alpha)$ with $\mathfrak{g}$ we get the Lie algebra $L(n, \alpha):=\mathfrak{g} \otimes A(n, \alpha)$, which we equip with the form

$$
\begin{equation*}
B(a \otimes(f,[p]), b \otimes(g,[q])):=\kappa(a, b) \mathrm{t}(f g,[p q]) . \tag{11}
\end{equation*}
$$

It is known that the bilinear form $B$ is symmetric non-degenerate and invariant.
Definition 2.3. Take an arbitrary sequence $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant-2\right)$ and let $A(0, \alpha):=F((x))$. We define the functional t: $A(0, \alpha) \rightarrow F$ by

$$
\mathrm{t}(f):=\operatorname{res}_{0}\{\alpha f\},
$$

where $\alpha=1+\alpha_{-2} x+\cdots \in F((x))$. We equip the Lie algebra $L(0, \alpha):=\mathfrak{g} \otimes A(0, \alpha)$ with the bilinear form

$$
\begin{equation*}
B(a \otimes f, b \otimes g):=\kappa(a, b) \mathrm{t}(f g), \tag{12}
\end{equation*}
$$

which is again symmetric non-degenerate and invariant. From now on we identify $F((x))$ with $F((x)) \times\{0\}$ and write $(f, 0)$ for elements in $A(0, \alpha)$.

Definition 2.4. A series of the form $\varphi=x+a_{2} x^{2}+a_{3} x^{3}+\cdots \in F \llbracket x \rrbracket$ is called a coordinate transformation. Coordinate transformations form a group $\mathrm{Aut}_{0} F \llbracket x \rrbracket$ under substitution which we view as a subgroup of automorphisms of $F \llbracket x \rrbracket$.

An element $\varphi \in \operatorname{Aut}_{0} F \llbracket x \rrbracket$ induces an automorphism of $A(n, \alpha)$ by $f / g \mapsto \varphi(f) / \varphi(g)$ and $[p] \mapsto[\varphi(p)]$ that changes the functional t to to $\varphi$. We write $A(n, \alpha)^{(\varphi)}$ for the algebra $A(n, \alpha)$ with the functional to $\varphi$. It is not hard to see that for any $\varphi \in \operatorname{Aut}_{0} F \llbracket x \rrbracket$ there is a sequence $\beta$ such that $A(n, \alpha)^{(\varphi)}=A(n, \beta)$.

Let $(L, \mathfrak{g} \llbracket x \rrbracket)$ be a topological Manin pair. According to [8, Proposition 2.9] as a Lie algebra with form $L \cong L(\infty)$ or $L \cong L(n, \alpha)$, for some $n \geqslant 0$ and some sequence $\alpha$. Here we identify $\mathfrak{g} \llbracket x \rrbracket$ with the diagonal

$$
\Delta:=\{(f,[f]) \mid f \in \mathfrak{g} \llbracket x \rrbracket\} \subset L(n, \alpha) .
$$

Moreover, we can assume that all the elements $\alpha_{i}$ in the sequence $\alpha$, except maybe $\alpha_{0}$, are 0 by virtue of the following result.

Proposition 2.5. [1, Proposition 3.12] Let $n \geqslant 0$ and $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ be a sequence. There exists $a \varphi \in \operatorname{Aut}_{0} F \llbracket x \rrbracket$ such that $A(n, \alpha) \cong A(n, \beta)^{(\varphi)}$, where $\beta$ is the sequence satisfying $\beta_{i}=0$ for all $i \neq 0$ and $\beta_{0}=\alpha_{0}$.

Remark 2.6. Observe that the result of Proposition 2.5 can be interpreted in terms of a formal differential equation. Consider an arbitrary $\alpha(x)=x^{-n}+\alpha_{n-2} x^{-n+1}+\cdots+\alpha_{0} x^{-1}+\cdots \in F((x))$ and $\beta(x)=x^{-n}+\alpha_{0} x^{-1}$. Then the functionals $\mathrm{t}_{\alpha}$ and $\mathrm{t}_{\beta}$ defined on $A(n, \alpha)$ and $A(n, \beta)$ respectively are given by

$$
\left.\mathrm{t}_{\alpha}(f,[p])=\operatorname{res}_{0}\{\alpha(f-p)\} \quad \text { and } \quad \mathrm{t}_{\beta}(f,[p])=\operatorname{res}_{0}\{\beta(f-p)\}\right)
$$

The equality $A(n, \alpha)^{(\varphi)}=A(n, \beta)$ can be expressed as

$$
\begin{equation*}
\operatorname{res}_{0}\{\beta(x) f(x)\}=\operatorname{res}_{0}\{\alpha(x) f(\varphi(x))\}=\operatorname{res}_{0}\left\{\alpha(\psi(x)) f(x) \psi^{\prime}(x)\right\} \tag{13}
\end{equation*}
$$

where $\psi \in \operatorname{Aut}_{0}(F \llbracket x \rrbracket)$ is the compositional inverse of $\varphi$, i.e. $\varphi(\psi(x))=x$. Since the residue pairing is nondegenerate on $F((x))$, we obtain

$$
\begin{equation*}
\alpha(\psi(x)) \psi^{\prime}(x)=\beta(x) \tag{14}
\end{equation*}
$$

In particular, the transformation $\varphi$ is the compositional inverse of the solution to Eq. (14)

## 3 Series of type $(n, s)$ and subspaces of $L(n, \alpha)$

Let $\left\{b_{i}\right\}_{i=1}^{d}$ be an othonormal basis of $\mathfrak{g}$ with respect to the Killing form $\kappa$. We write $\Omega$ for the quadratic Casimir element $\sum_{i=1}^{d} b_{i} \otimes b_{i} \in \mathfrak{g} \otimes \mathfrak{g}$. It satisfies the identity $[a \otimes 1+1 \otimes a, \Omega]=0$ for all $a \in \mathfrak{g}$.

In this section we describe a bijection between subspaces $W \subset L(n, \alpha)$ complementary to $\Delta$ and certain series. The following definition introduces convenient spaces containing these series.

Definition 3.1. We put $A_{1}(n, \alpha):=A(n, \alpha)=F\left(\left(x_{1}\right)\right) \oplus F\left[x_{1}\right] /\left(x_{1}^{n}\right)$ and then define inductively the algebras

$$
\begin{equation*}
A_{m}(n, \alpha):=A_{m-1}(n, \alpha)\left(\left(x_{m}\right)\right) \oplus A_{m-1}(n, \alpha)\left[x_{m}\right] / x_{m}^{n} A_{m-1}(n, \alpha), m>1 \tag{15}
\end{equation*}
$$

The functional t defined on $A(n, \alpha)$ extends inductively to a functional on $A_{m}(n, \alpha)$. More precisely,

$$
\begin{equation*}
\mathrm{t}\left(\sum_{k \geqslant-N} f_{k} x_{m}^{k}, \sum_{\ell=0}^{n-1}\left[g_{\ell} x_{m}^{\ell}\right]\right):=\sum_{k \geqslant-N} \mathrm{t}\left(f_{k}\right) \mathrm{t}\left(x_{m}^{k}, 0\right)+\sum_{\ell=0}^{n-1} \mathrm{t}\left(g_{\ell}\right) \mathrm{t}\left(0,\left[x_{m}\right]^{\ell}\right), \tag{16}
\end{equation*}
$$

where $f_{k}, g_{\ell} \in A_{m-1}(n, \alpha)$. Since $\mathrm{t}\left(x^{n} F \llbracket x \rrbracket\right)=0$, the sum on the right-hand side of Eq. (16) is finite and well-defined. This allows us to extend the form $B$ on $L(n, \alpha)$ to a symmetric non-degenerate bilinear form on the $\mathfrak{g}$-module

$$
\begin{equation*}
L_{m}(n, \alpha):=\mathfrak{g}^{\otimes m} \otimes A_{m}(n, \alpha) \tag{17}
\end{equation*}
$$

by letting

$$
\begin{equation*}
B\left(\left(a_{1} \otimes \ldots \otimes a_{m}\right) \otimes f,\left(b_{1} \otimes \ldots \otimes b_{m}\right) \otimes g\right):=\mathrm{t}(f g) \prod_{k=1}^{m} \kappa\left(a_{k}, b_{k}\right) \tag{18}
\end{equation*}
$$

for all $a_{1}, \ldots, a_{m}, b_{1}, \ldots, b_{m} \in \mathfrak{g}$ and $f, g \in A_{m}(n, \alpha)$.

Fix some integer $n \geqslant 0$. We interpret the quotient $y^{n} \Omega /(x-y)$ in the following way

$$
\begin{align*}
\frac{y^{n} \Omega}{x-y} & =\sum_{k=0}^{n-1} \sum_{i=1}^{d} b_{i}\left(0,-[x]^{(n-1)-k}\right) \otimes b_{i}\left(y^{k},[y]^{k}\right)+\sum_{k=n}^{\infty} \sum_{i=1}^{d} b_{i}\left(x^{(n-1)-k}, 0\right) \otimes b_{i}\left(y^{k}, 0\right)  \tag{19}\\
& =\sum_{k=0}^{\infty} \sum_{i=1}^{d} w_{k, i} \otimes b_{i}\left(y^{k},[y]^{k}\right) \in(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket \subset L_{2}(n, \alpha),
\end{align*}
$$

where $\alpha$ is an arbitrary sequence and we write $b_{i}\left(x^{\ell},[x]^{m}\right)$ meaning $b_{i} \otimes\left(x^{\ell},[x]^{m}\right)$.
Definition 3.2. Since $(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket$ is an $F \llbracket x \rrbracket \cong F \llbracket(x,[x]) \rrbracket$-module and

$$
(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket \cong(\Delta \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket \subset(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket
$$

the series

$$
\begin{equation*}
r(x, y)=\frac{s(x) y^{n} \Omega}{x-y}+g(x, y) \tag{20}
\end{equation*}
$$

where $g \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ and $s \in F \llbracket x \rrbracket^{\times}$, is also inside $(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket$. Series of the form Eq. (20) are called series of type $(n, s)$.

Remark 3.3. Every series

$$
r(x, y)=\frac{h(x, y) \Omega}{x-y}+g(x, y) \in L_{2}(n, \alpha)
$$

where $h \in F \llbracket x, y \rrbracket, h(x, x) \neq 0$ and $g \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$, has a unique representation as a series of type $(n, s)$. Indeed, write $h(x, x)=x^{n} s(x)$ for some $s \in F \llbracket x \rrbracket^{\times}$. Then $h(x, y)-y^{n} s(x)=(x-y) f(x, y)$ for some $f \in F \llbracket x, y \rrbracket$. This implies that we can rewrite $r$ in the $(n, s)$ form

$$
\begin{equation*}
r(x, y)=\frac{s(x) y^{n} \Omega}{x-y}+f(x, y) \Omega+g(x, y) \tag{21}
\end{equation*}
$$

In the construction of $f$ we are using the fact that for any $F$-vector space $V$ and any element $h \in V \llbracket x, y \rrbracket$

$$
\begin{equation*}
h(z, z)=0 \Longrightarrow h(x, y)=(x-y) f(x, y) \tag{22}
\end{equation*}
$$

for some $f \in V \llbracket x, y \rrbracket$.
Definition 3.4. For each series $r$ of type $(n, s)$ we define another series $\bar{r}$ of the same type $(n, s)$ by

$$
\begin{equation*}
\bar{r}(x, y):=\frac{s(y) x^{n} \Omega}{x-y}-\tau(g(y, x)) \in(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket, \tag{23}
\end{equation*}
$$

where $\tau$ is the $F \llbracket x, y \rrbracket$-linear extension of the map $a \otimes b \mapsto b \otimes a$. To see that this is an $(n, s)$-type series its enough to apply the argument from Remark 3.3. Series of type ( $n, s$ ), satisfying $r=\bar{r}$, are called skew-symmetric.

Definition 3.5. The generalized classical Yang-Baxter equation $(G C Y B E)$ is the equation for an $(n, s)$-type series of the form

$$
\begin{equation*}
\operatorname{GCYB}(r):=\left[r^{12}\left(x_{1}, x_{2}\right), r^{13}\left(x_{1}, x_{3}\right)\right]+\left[r^{12}\left(x_{1}, x_{2}\right), r^{23}\left(x_{2}, x_{3}\right)\right]+\left[r^{13}\left(x_{1}, x_{3}\right), \bar{r}^{23}\left(x_{2}, x_{3}\right)\right]=0 \tag{24}
\end{equation*}
$$

Here $(-)^{13}: L_{2}(n, \alpha) \rightarrow(U(\mathfrak{g}) \otimes U(\mathfrak{g}) \otimes U(\mathfrak{g})) \otimes A_{3}(n, \alpha)$ is the inclusion map given by
$a \otimes b \otimes\left(\sum_{k \geqslant-N} F\left(x_{1},\left[x_{1}\right]\right) x_{2}^{k}, \sum_{m=0}^{n-1} G\left(x_{1},\left[x_{1}\right]\right)\left[x_{2}\right]^{m}\right) \mapsto a \otimes 1 \otimes b \otimes\left(\sum_{k \geqslant-N} F\left(x_{1},\left[x_{1}\right]\right) x_{3}^{k}, \sum_{m=0}^{n-1} G\left(x_{1},\left[x_{1}\right]\right)\left[x_{3}\right]^{m}\right)$.
Other inclusions are defined in a similar manner. The commutators are then taken in the associative $A_{3}(n, \alpha)$ algebra $(U(\mathfrak{g}) \otimes U(\mathfrak{g}) \otimes U(\mathfrak{g})) \otimes A_{3}(n, \alpha)$.

Before formulating the main theorem of the section we note that if $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ is an arbitrary sequence and $\alpha(x)=x^{-n}+\alpha_{n-2} x^{-n+1}+\cdots+\alpha_{0} x^{-1}+\cdots \in F((x))$ is the corresponding series, then $x^{n} \alpha(x) \in F \llbracket x \rrbracket^{\times}$.

Theorem 3.6. Let $n \in \mathbb{Z}_{\geqslant 0}$ and $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ be an arbitrary sequence with the corresponding series $\alpha(x) \in F((x))$. Consider the map

$$
W: L_{2}(n, \alpha) \longrightarrow\{V \subset L(n, \alpha) \mid V \text { is a subspace }\}
$$

given by

$$
\sum_{i, j} b_{i} \otimes b_{j} \otimes\left(\sum_{k \geqslant-N_{i}}\left(f_{k}^{i j},\left[p_{k}^{i j}\right]\right) x^{k}, \sum_{m=0}^{n-1}\left(g_{m}^{i j},\left[q_{m}^{i j}\right]\right)[x]^{m}\right) \mapsto \operatorname{span}_{F}\left\{b_{i}\left(f_{k}^{i j},\left[p_{k}^{i j}\right]\right) \mid k \geqslant-N, 1 \leqslant i, j \leqslant d\right\} .
$$

The following results are true:

1. W defines a bijection between series of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ and subspaces $V \subseteq L(n, \alpha)$ complementary to the diagonal $\Delta$, i.e. $L(n, \alpha)=\Delta \dot{+} V$;
2. For any series $r$ of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ we have $W(r)^{\perp}=W(\bar{r})$ inside $L(n, \alpha)$;
3. Any series $r$ of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ satisfies $\operatorname{GCYB}(r)=\psi$, where $\psi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket\left(x_{1},\left[x_{1}\right]\right),\left(x_{2},\left[x_{2}\right]\right),\left(x_{3},\left[x_{3}\right]\right) \rrbracket$ is defined by

$$
B\left(v_{1} \otimes v_{2} \otimes v_{3}, \psi\right)=B\left(v_{1},\left[v_{2}, v_{3}\right]\right)
$$

for all $v_{1} \in W(\bar{r}), v_{2}, v_{3} \in W(r)$.
Proof. Fix an $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$-type series

$$
\begin{aligned}
r(x, y) & =\frac{1}{x^{n} \alpha(x)} \frac{y^{n} \Omega}{x-y}+g(x, y) \\
& =\sum_{k=0}^{\infty} \sum_{i=1}^{d} s_{k, i} \otimes b_{i}\left(y^{k},[y]^{k}\right)+\sum_{k=0}^{\infty} \sum_{i=1}^{d} g_{k, i} \otimes b_{i}\left(y^{k},[y]^{k}\right) \in(L(n, \alpha) \otimes \mathfrak{g}) \llbracket(y,[y]) \rrbracket .
\end{aligned}
$$

It is easy to see that

$$
U:=\operatorname{span}_{F}\left\{w_{k, i} \mid k \geqslant 0,1 \leqslant k \leqslant d\right\} \subset L(n, \alpha),
$$

where $w_{k, i}$ are defined in Eq. (19), satisfies the condition $\Delta \dot{+} U=L(n, \alpha)$. Since $s:=\frac{1}{x^{n} \alpha(x)}$ is invertible, we have $s U \dot{+} s \Delta=s U \dot{+} \Delta=L(n, \alpha)$. In other words, the space

$$
\begin{equation*}
s U=\operatorname{span}_{F}\left\{s_{k, i}=s w_{k, i} \mid k \geqslant 0,1 \leqslant k \leqslant d\right\} \subset L(n, \alpha) \tag{25}
\end{equation*}
$$

is also complementary to the diagonal. Finally, since $g_{k, i} \in \Delta$ the space

$$
W(r)=\operatorname{span}_{F}\left\{s w_{k, i}+g_{k, i} \mid k \geqslant 0,1 \leqslant k \leqslant d\right\} \subset L(n, \alpha)
$$

is complementary to the diagonal. Conversely, if $V \subset L(n, \alpha)$ satisfies $V \dot{+} \Delta=L(n, \alpha)$, then for each $k \geqslant 0$ and $1 \leqslant i \leqslant d$ we can find a unique $g_{k, i} \in \Delta$ such that $s w_{k, i}+g_{k, i} \in V$. Define the $(n, s)$ series $r_{V}$ by

$$
r_{V}(x, y)=\sum_{k \geqslant 0} \sum_{i=1}^{d}\left(s w_{k, i}+g_{k, i}\right) \otimes b_{i}\left(y^{k},[y]^{k}\right) .
$$

It is now clear, that $W\left(r_{V}\right)=V$. These constructions establish the bijection in part 1.
To prove the second statement, observe that

$$
\begin{equation*}
B\left(s w_{k, i}, b_{j}\left(y^{\ell},[y]^{\ell}\right)\right)=\delta_{i, j} \delta_{k, \ell} . \tag{26}
\end{equation*}
$$

Furthermore, the straightforward calculation shows that

$$
\begin{aligned}
B\left(s w_{k, i}, s w_{\ell, j}\right) & = \begin{cases}-\operatorname{res}_{0}\left\{s x^{(n-1)-k-\ell-1}\right\} & \text { if } i=j \text { and } 0 \leqslant k, \ell \leqslant n-1, \\
\operatorname{res}_{0}\left\{s x^{(n-1)-k-\ell-1}\right\} & \text { if } i=j \text { and } k, \ell \geqslant n, \\
0 & \text { otherwise, }\end{cases} \\
& = \begin{cases}-s_{k+\ell-n+1} & \text { if } i=j, 0 \leqslant k, \ell \leqslant n-1 \text { and } k+\ell \geqslant n-1, \\
s_{k+\ell-n+1} & \text { if } i=j \text { and } k, \ell \geqslant n, \\
0 & \text { otherwise, }\end{cases}
\end{aligned}
$$

where $s(x)=\sum_{k=0}^{\infty} s_{k} x^{k}$. We write

$$
\begin{aligned}
\bar{r}(x, y) & =\frac{s(y) x^{n} \Omega}{x-y}-\tau(g(y, x))=\frac{s(x) y^{n} \Omega}{x-y}-\frac{\left(s(x) y^{n}-s(y) x^{n}\right) \Omega}{x-y}-\tau(g(y, x)) \\
& =\sum_{k \geqslant 0} \sum_{i=1}^{d}\left(s w_{k, i}+\bar{g}_{k, i}\right) \otimes b_{i}\left(y^{k},[y]^{k}\right)
\end{aligned}
$$

Consider the quotient

$$
\begin{aligned}
& \frac{\left(s(x) y^{n}-s(y) x^{n}\right) \Omega}{x-y}=\frac{y^{n}(s(x)-s(y)) \Omega}{x-y}-\frac{s(y)\left(x^{n}-y^{n}\right) \Omega}{x-y} \\
& =\sum_{k \geqslant 0} \sum_{i=1}^{d} s_{k}\left(\sum_{\ell=1}^{k} b_{i}\left(x^{k-\ell},[x]^{k-\ell}\right) \otimes b_{i}\left(y^{(n-1)+\ell},[y]^{(n-1)+\ell}\right)-\sum_{\ell=1}^{n} b_{i}\left(x^{n-\ell},[x]^{n-\ell}\right) \otimes b_{i}\left(y^{k+\ell-1},[y]^{k+\ell-1}\right)\right) .
\end{aligned}
$$

The coefficient of $b_{i}\left(x^{k},[x]^{k}\right) \otimes b_{i}\left(y^{\ell},[y]^{\ell}\right)$ in the expression above is

$$
\begin{aligned}
-s_{k+\ell-(n-1)} & \text { if } 0 \leqslant k, \ell \leqslant n-1 \text { and } k+\ell \geqslant n-1 \\
s_{k+\ell-(n-1)} & \text { if } k, \ell \geqslant n
\end{aligned}
$$

which coincides with $B\left(s w_{k, i}, s w_{\ell, i}\right)$. If we now expand the coefficients $g_{k, i}$ in the following way

$$
g_{k, i}=\sum_{\ell \geqslant 0} \sum_{j=1}^{d} g_{k, i}^{\ell, j} b_{j}\left(x^{\ell},[x]^{\ell}\right)
$$

the coefficients $\bar{g}_{k, i}$ can be rewritten as

$$
\bar{g}_{k, i}=-\sum_{\ell \geqslant 0} \sum_{j=1}^{d}\left(g_{\ell, j}^{k, i}+B\left(s w_{k, i}, s w_{\ell, j}\right)\right) b_{i}\left(x^{k},[x]^{k}\right) \otimes b_{j}\left(y^{\ell},[y]^{\ell}\right) .
$$

Combining all the results above we obtain the desired equality

$$
\begin{aligned}
B\left(s w_{k, i}+g_{k, i}, s w_{\ell, j}+\bar{g}_{\ell, j}\right) & =B\left(s w_{k, i}, s w_{\ell, j}\right)+B\left(s w_{k, i}, \bar{g}_{\ell, j}\right)+B\left(g_{k, i}, s w_{\ell, j}\right)+B\left(g_{k, i}, \bar{g}_{\ell, j}\right) \\
& =B\left(s w_{k, i}, s w_{\ell, j}\right)+\left(-g_{k, i}^{\ell, j}-B\left(s w_{k, i}, s w_{\ell, j}\right)\right)+g_{k, i}^{\ell, j}+0 \\
& =0
\end{aligned}
$$

which completes the proof of the second statement.
Using the same technique as in [2, Section 1], one can prove that

$$
\psi:=\operatorname{GCYB}(r) \in(\Delta \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket\left(x_{2},\left[x_{2}\right]\right),\left(x_{3},\left[x_{3}\right]\right) \rrbracket
$$

for any series $r$ of type $(n, s)$. Define $r_{k, i}:=s w_{k, i}+g_{k, i}$ and $\bar{r}_{k, i}:=s w_{k, i}+\bar{g}_{k, i}$ and rewrite GCYB $(r)$ as

$$
\begin{align*}
\psi= & \sum_{k, \ell \geqslant 0} \sum_{i, j=1}^{d}\left[r_{k, i}, r_{\ell, j}\right] \otimes b_{i}\left(x_{2}^{k},\left[x_{2}\right]^{k}\right) \otimes b_{j}\left(x_{3}^{\ell},\left[x_{3}\right]^{\ell}\right)  \tag{27}\\
& +\sum_{k \geqslant 0} \sum_{i=1}^{d} r_{k, i} \otimes\left(\left[b_{i}\left(x_{2}^{k},\left[x_{2}\right]^{k}\right) \otimes(1,1), r\left(x_{2}, x_{3}\right)\right]+\left[(1,1) \otimes b_{i}\left(x_{3}^{k},\left[x_{3}\right]^{k}\right), \bar{r}\left(x_{2}, x_{3}\right)\right]\right) .
\end{align*}
$$

Applying $B\left(\bar{r}_{k_{1}, i_{1}} \otimes r_{k_{2}, i_{2}} \otimes r_{k_{3}, i_{3}},-\right)$ to the equation above, we get

$$
\begin{equation*}
B\left(\bar{r}_{k_{1}, i_{1}} \otimes r_{k_{2}, i_{2}} \otimes r_{k_{3}, i_{3}}, \psi\right)=B\left(\bar{r}_{k_{1}, i_{1}},\left[r_{k_{2}, i_{2}}, r_{k_{3}, i_{3}}\right]\right) \tag{28}
\end{equation*}
$$

This gives the last statement because $W(r)$ and $W(\bar{r})$ are generated by $r_{k, i}$ and $\bar{r}_{k, i}$ respectively.
Corollary 3.7. Let $n \in \mathbb{Z}_{\geqslant 0}, \alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ and $W$ be as in Theorem 3.6. Then

1. $W$ defines a bijection between skew-symmtric $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$-type series and Lagrangian subspaces $V \subseteq L(n, \alpha)$ complementary to the diagonal $\Delta$;
2. W defines a bijection between $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$-type series solving $G C Y B E$ and subalgebras $V \subseteq L(n, \alpha)$ complementary to the diagonal $\Delta$.

As we can see from the proof of Theorem 3.6 the element $\psi$ in $\operatorname{GCYB}(r)=\psi$ represents the obstruction for $W(r)$ from being a Lie subalgebra. This observation raises an interesting question that we do not consider in this paper: what elements $\psi$ can appear on the right-hand side of the above-mentioned equation.

Observe that if $r$ is a series of type $(n, s)$ and it satisfies

$$
\begin{equation*}
\operatorname{CYB}(r):=\left[r^{12}\left(x_{1}, x_{2}\right), r^{13}\left(x_{1}, x_{3}\right)\right]+\left[r^{12}\left(x_{1}, x_{2}\right), r^{23}\left(x_{2}, x_{3}\right)\right]+\left[r^{13}\left(x_{1}, x_{3}\right), r^{23}\left(x_{2}, x_{3}\right)\right]=\psi \tag{29}
\end{equation*}
$$

for some $\psi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y, z \rrbracket$, then $r$ is automatically skew-symmetric and hence solves the first equation as well. To prove that one can e.g. repeat the argument from [1, Lemma 5.2]. In other words, for a fixed $\psi$ solutions to $\mathrm{CYB}(r)=\psi$ form a subclass of solutions to $\operatorname{GCYB}(r)=\psi$. In particular, solutions to $\mathrm{CYB}(r)=0$. are exactly the skew-symmetric solutions to $\operatorname{GCYB}(r)=0$. We call the equation CYB $(r)=\psi$ Manin- Yang-Baxter equation.

Remark 3.8. As our notation suggest, we could have interpreted $y^{n} \Omega /(x-y)$ as

$$
\frac{y^{n} \Omega}{x-y}=\sum_{k \geqslant 0} \sum_{i=1}^{d} b_{i} x^{-k-1} \otimes b_{i} y^{n+k} \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket
$$

and performed all the arithmetic calculations in this form. To restore an $(n, s)$-type series from

$$
\begin{equation*}
\frac{s(x) y^{n} \Omega}{x-y}+g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket \tag{30}
\end{equation*}
$$

we can simply view $s(x) \in F \llbracket x \rrbracket^{\times}$and $g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ as elements in $F \llbracket(x,[x]) \rrbracket^{\times}$and $(\mathfrak{g} \otimes \mathfrak{g}) \llbracket(x,[x]),(y,[y]) \rrbracket$ respectively and reinterpret the singular part $y^{n} \Omega /(x-y)$ as it was done in Eq. (19).

Conversely, to get a series of the form Eq. (30) from a series of type $(n, s)$ we can just project the latter onto the first component.

In other words, we have a bijection between $(n, s)$-type series in $L_{2}(n, \alpha)$ and their projections Eq. (30) onto the first component given by different interpretations of the singular part $y^{n} \Omega /(x-y)$.

Although, all arithmetic operations can be performed in the form Eq. (30) the construction of $W(r)$ and statements like $\Delta \cap W(r)=0$ require us to pass to the interpretation Eq. (19). This is our main motivation to work directly with $(n, s)$-type series in $L_{2}(n, \alpha)$ instead of their projections.

In view of Remark 3.8, we have a new proof of 1, Corollary 5.5].
Corollary 3.9. Classical (formal) r-matrices, i.e. skew-symmetric elements

$$
\begin{equation*}
\frac{s(x) y^{n} \Omega}{x-y}+g(x, y)=\frac{1}{x^{n} \alpha(x)} \frac{y^{n} \Omega}{x-y}+g(x, y) \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket \tag{31}
\end{equation*}
$$

solving GCYBE, are in bijection with skew-symmetric series of type $(n, s)$ solving GCYBE and hence in bijection with Lagrangian Lie subalgebras of $L(n, \alpha)$ complementary to the diagonal $\Delta$.

The result of [1, Theorem 5.6] can be now formulated in the following way.
Corollary 3.10. Skew-symmetric series of type $\left(n, \frac{1}{x^{n} \alpha(x)}\right)$ that also solve GCYBE exist only for $n=0,1$ and $n=2$ with $\alpha_{0}=0$.

## 4 Quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$

We remind that $F$ is a discrete algebraically closed field of characteristic 0 and $\mathfrak{g} \llbracket x \rrbracket$ is an $F$-Lie algebra equipped with the $(x)$-adic topology.

As we now know, series of type $\left(n, 1 /\left(x^{n} \alpha(x)\right)\right)$ solving CYBE Eq. (29) are in bijection with Lagrangian subalgebras $W \subset L(n, \alpha)$ complementary to the diagonal. On the other hand, such Lagrangian subalgebras are in bijection with non-degenerate topological Lie bialgebra structures. See [1] for their definition and classification.

It turns out, that if we drop the condition on $W$ being a subalgebra, we get so called (non-degenerate) topological quasi-Lie bialgebras. This section is devoted to their classification up to topological twists and coordinate transformations.

Definition 4.1. A topological quasi-Lie bialgebra structure on $\mathfrak{g} \llbracket x \rrbracket$ consists of

- a skew-symmetric continuous linear map $\delta: \mathfrak{g} \llbracket x \rrbracket \rightarrow(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ and
- a skew-symmetric element $\varphi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y, z \rrbracket$,
which are subject to the following conditions

1. $\delta([a, b])=[a \otimes 1+1 \otimes a, \delta(b)]-[b \otimes 1+1 \otimes b, \delta(a)]$, i.e. $\delta$ is a 1 -cocycle;
2. $\quad \frac{1}{2} \operatorname{Alt}((\delta \otimes 1) \delta(a))=[a \otimes 1 \otimes 1+1 \otimes a \otimes 1+1 \otimes 1 \otimes a, \varphi] ;$
3. $\quad \operatorname{Alt}((\delta \otimes 1 \otimes 1) \varphi)=0$,
where $\operatorname{Alt}\left(x_{1} \otimes \ldots \otimes x_{n}\right):=\sum_{\sigma \in S_{n}} \operatorname{sgn}(\sigma) x_{\sigma(1)} \otimes \ldots \otimes x_{\sigma(n)}$.
Lemma 4.2. There is a one-to-one correspondence between triples ( $L, \mathfrak{g} \llbracket x \rrbracket, W$ ), where ( $L, \mathfrak{g} \llbracket x \rrbracket$ ) is a topological Manin pair and $W \subset L$ is a Lagrangian subspace satisfying $W+\mathfrak{g} \llbracket x \rrbracket=L$, and quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$.

Proof. We start with a topological Manin pair $(L, \mathfrak{g} \llbracket x \rrbracket)$. If $W \subset L$ is a Lagrangian subspace complementary to $\mathfrak{g} \llbracket x \rrbracket$, then it is easy to see that $W \cong \mathfrak{g} \llbracket x \rrbracket^{\prime}$. Therefore, we have an isomorphism of vector spaces

$$
L \cong \mathfrak{g} \llbracket x \rrbracket \dot{+} \mathfrak{g} \llbracket x \rrbracket^{\prime}
$$

The form on $L$ under this isomorphism becomes standard evaluation form $\langle-,-\rangle$ on $\mathfrak{g} \llbracket x \rrbracket \dot{+} \mathfrak{g} \llbracket x \rrbracket^{\prime}$. We fix such an isomorphism.

Let us define two linear functions

$$
p_{1}: \mathfrak{g} \llbracket x \rrbracket^{\prime} \otimes \mathfrak{g} \llbracket y \rrbracket^{\prime} \rightarrow \mathfrak{g} \llbracket x \rrbracket \text { and } p_{2}: \mathfrak{g} \llbracket x \rrbracket^{\prime} \otimes \mathfrak{g} \llbracket y \rrbracket^{\prime} \rightarrow \mathfrak{g} \llbracket x \rrbracket^{\prime}
$$

by $[f, g]=p_{1}(f \otimes g)+p_{2}(f \otimes g)$. We put

$$
\delta:=p_{2}^{\vee}:\left(\mathfrak{g} \llbracket x \rrbracket^{\prime}\right)^{\vee} \cong \mathfrak{g} \llbracket x \rrbracket \rightarrow\left(\mathfrak{g} \llbracket x \rrbracket^{\prime} \otimes \mathfrak{g} \llbracket y \rrbracket^{\prime}\right)^{\vee} \cong(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket,
$$

and let $\psi \in(\mathfrak{g} \otimes \mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y, z \rrbracket$ be the unique element satisfying the condition

$$
\begin{equation*}
\langle h,[f, g]\rangle=\left\langle h, p_{1}(f \otimes g)\right\rangle=\langle f \otimes g \otimes h, \psi\rangle \text { for all } f, g, h \in \mathfrak{g} \llbracket x \rrbracket^{\prime} . \tag{32}
\end{equation*}
$$

The skew-symmetry of $p_{2}$ implies the skew-symmetry of $\delta$, whereas the skew-symmetry of $p_{1}$ and the invariance of the evaluation form yield the skew-symmetry of $\psi$.

Next, we observe that for all $a, b \in \mathfrak{g} \llbracket x \rrbracket$ and $f, g \in \mathfrak{g} \llbracket x \rrbracket^{\prime}$ we have

$$
\begin{aligned}
& \langle[a, f], g\rangle=\langle a,[f, g]\rangle=\left\langle a, p_{2}(f \otimes g)\right\rangle=\langle\delta(a), f \otimes g\rangle=\langle(f \otimes 1) \delta(a), g\rangle \\
& \langle[a, f], b\rangle=-\langle f,[a, b]\rangle=-\left\langle f \circ \operatorname{ad}_{a}, b\right\rangle
\end{aligned}
$$

In other words, the invariance of the form forces the following equality to hold

$$
\begin{equation*}
[a, f]=-f \circ \operatorname{ad}_{a}+(f \otimes 1) \delta(a) \tag{33}
\end{equation*}
$$

Using Eq. (33) and non-degeneracy of the form we show that $\delta$ is a 1-cocycle:

$$
\begin{align*}
\langle\delta([a, b]), f \otimes g\rangle & =\left\langle[a, b], p_{2}(f \otimes g)\right\rangle=\langle[a, b],[f, g]\rangle=\langle[[a, b], f], g\rangle=\langle-[[b, f], a]-[[f, a], b], g\rangle \\
& =\left\langle\left[f \circ \operatorname{ad}_{b}-(f \otimes 1) \delta(b), a\right]-\left[f \circ \operatorname{ad}_{a}-(f \otimes 1) \delta(a), b\right], g\right\rangle \\
& =-\left\langle a,\left[f \circ \operatorname{ad}_{b}, g\right]\right\rangle+\left\langle b,\left[f \circ \operatorname{ad}_{a}, g\right]\right\rangle+\left\langle\left(f \otimes \operatorname{ad}_{a}\right) \delta(b), g\right\rangle-\left\langle\left(f \otimes \operatorname{ad}_{b}\right) \delta(a), g\right\rangle  \tag{34}\\
& =\langle[a \otimes 1+1 \otimes a, \delta(b)]-[b \otimes 1+1 \otimes b, \delta(a)], f \otimes g\rangle .
\end{align*}
$$

The 1-cocycle condition implies that $\delta$ is continuous as it was noted in [1, Remark 3.16].
For conditions 2 and 3 from the definition of a topological quasi-Lie bialgebra consider the Jacobi identity for $f, g, h \in \mathfrak{g} \llbracket x \rrbracket^{\prime}:$

$$
\begin{align*}
0= & {\left[p_{1}(f \otimes g), h\right]+\left[p_{1}(g \otimes h), f\right]+\left[p_{1}(h \otimes f), g\right] } \\
& +p_{1}\left(p_{2}(f \otimes g) \otimes h\right)+p_{1}\left(p_{2}(g \otimes h) \otimes f\right)+p_{1}\left(p_{2}(h \otimes f) \otimes g\right)  \tag{35}\\
& +p_{2}\left(p_{2}(f \otimes g) \otimes h\right)+p_{2}\left(p_{2}(g \otimes h) \otimes f\right)+p_{2}\left(p_{2}(h \otimes f) \otimes g\right)
\end{align*}
$$

We denote by $\circlearrowleft$ the summation over circular permutations of symbols $f, g$ and $h$, e.g. $\circlearrowleft\left\langle p_{1}(f \otimes g), h\right\rangle=$ $\left\langle p_{1}(f \otimes g), h\right\rangle+\left\langle p_{1}(g \otimes h), f\right\rangle+\left\langle p_{1}(h \otimes f), g\right\rangle$. Applying $\langle-, a\rangle$ to Eq. (35) for an arbitrary $a \in \mathfrak{g} \llbracket x \rrbracket$ gives

$$
\begin{aligned}
\left\langle p_{2}\left(p_{2} \otimes 1\right)(\circlearrowleft f \otimes g \otimes h), a\right\rangle & =-\left\langle\circlearrowleft\left[p_{1}(f \otimes g), h\right], a\right\rangle \\
\left\langle p_{2} \otimes 1(\circlearrowleft f \otimes g \otimes h), \delta(a)\right\rangle & =\circlearrowleft\left\langle-h \circ \operatorname{ad}_{a}, p_{1}(f \otimes g)\right\rangle \\
\langle\circlearrowleft f \otimes g \otimes h,(\delta \otimes 1) \delta(a)\rangle & =\circlearrowleft\left\langle f \otimes g \otimes\left(-h \circ \operatorname{ad}_{a}\right), \psi\right\rangle \\
\langle f \otimes g \otimes h, \operatorname{Alt}((\delta \otimes 1) \delta(a)) / 2\rangle & =-\langle f \otimes g \otimes h,[1 \otimes 1 \otimes a+1 \otimes a \otimes 1+a \otimes 1 \otimes 1, \psi]\rangle,
\end{aligned}
$$

where the very last identity holds because of the skew-symmetry of $\psi$. Multiplying this equality by 2 we get the relation

$$
\langle f \otimes g \otimes h, \operatorname{Alt}((\delta \otimes 1) \delta(a))+2[1 \otimes 1 \otimes a+1 \otimes a \otimes 1+a \otimes 1 \otimes 1, \psi]\rangle=0
$$

Letting $\varphi:=-\psi$ we obtain the second identity from the definition of a topological quasi-Lie bialgebra structure. Applying instead $\langle s,-\rangle, s \in \mathfrak{g} \llbracket x \rrbracket^{\prime}$ to the Jacobi identity Eq. (35) we get the desired

$$
\operatorname{Alt}((\delta \otimes 1 \otimes 1) \psi)=0
$$

Therefore, $(\mathfrak{g} \llbracket x \rrbracket, \delta, \varphi)$ is a topological quasi-Lie bialgebra.
For the converse direction, we put $L:=\mathfrak{g} \llbracket x \rrbracket \dot{+} \mathfrak{g} \llbracket x \rrbracket^{\prime}$ with the standard evaluation form; we let $p_{1}$ be the unique element in $\operatorname{Hom}_{F-\operatorname{Vect}}\left(\mathfrak{g} \llbracket x \rrbracket^{\prime} \otimes \mathfrak{g} \llbracket x \rrbracket^{\prime}, \mathfrak{g} \llbracket x \rrbracket\right)$ satisfying Eq. (32) with $\psi:=-\varphi$; we define $p_{2}:=\delta^{\prime}$, i.e. the dual map of $\delta$. The Lie bracket between two elements in $\mathfrak{g} \llbracket x \rrbracket^{\prime}$ is given by the sum $p_{1}+p_{2}$. Defining $[a, f]$ as in Eq. (33) the evaluation form becomes invariant and we get a topological Manin pair ( $L, \mathfrak{g} \llbracket x \rrbracket$ ) with the Lagrangian subspace $\mathfrak{g} \llbracket x \rrbracket^{\prime}$. These constructions are clearly inverse to each other.

Combining the classification of Manin pairs mentioned in Section 2 with Corollary 3.7 and Lemma 4.2 we get the following description of all topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$.

Lemma 4.3. There is a bijection between topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$ and Lagrangian subspaces $W \subset L(n, \alpha)$ or $L(\infty)$ complementary to the diagonal $\Delta$, where $\alpha=\left(\alpha_{i} \in F \mid-\infty<i \leqslant n-2\right)$ is an arbitrary sequence and $n \geqslant 0$. Moreover, such Lagrangian subspaces $W \subset L(n, \alpha)$ are in bijection with skew-symmetric sequences of type $\left(n, 1 /\left(x^{n} \alpha(x)\right)\right)$.

In view of this result we call skew-symmetric series of type $(n, s)$ as well as their projections onto the first component quasi-r-matrices. Quasi-Lie bialgebra structures can also be described using their associated quasi-$r$-matrices in the following way.

Proposition 4.4. Assume $(\mathfrak{g} \llbracket x \rrbracket, \delta, \varphi)$ is a topological quasi-Lie bialgebra and let $r \in L_{2}(n, \alpha)$ be the corresponding quasi-r-matrix given by the bijection from Lemma 4.3. Under the identification $\mathfrak{g} \llbracket(x,[x]) \rrbracket \cong \mathfrak{g} \llbracket x \rrbracket$ we have the following identities:

- $\quad[a \otimes 1+1 \otimes a, r]=-\delta(a)$ for any $a \in \mathfrak{g} \llbracket x \rrbracket$ and
- $\quad \mathrm{CYB}(r)=-\varphi$.

The same is true for the projection $r \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket$.
Proof. We start, as in the proof of Lemma 4.2. by fixing an identification $L(n, \alpha)=\Delta \dot{+} W(r) \cong \mathfrak{g} \llbracket x \rrbracket \dot{+} \mathfrak{g} \llbracket x \rrbracket^{\prime}$. Let $\left\{v_{k, i}\right\}$ be a basis for $\mathfrak{g} \llbracket x \rrbracket^{\prime}$ dual to $\left\{\varepsilon_{k, i}:=b_{i} y^{k}\right\}$. Then $r=\sum_{k \geqslant 0} \sum_{i=1}^{d} v_{k, i} \otimes \varepsilon_{k, i}$ and we have

$$
\begin{aligned}
{[a \otimes 1+1 \otimes a, r] } & =\sum_{k \geqslant 0} \sum_{i=1}^{d}\left[a, v_{k, i}\right] \otimes \varepsilon_{k, i}+v_{k, i} \otimes\left[a, \varepsilon_{k, i}\right] \\
& =\sum_{k \geqslant 0} \sum_{i=1}^{d}\left(-v_{k, i} \circ \operatorname{ad}_{a}+\left(v_{k, i} \otimes 1\right) \delta(a)\right) \otimes \varepsilon_{k, i}+v_{k, i} \otimes\left[a, \varepsilon_{k, i}\right]
\end{aligned}
$$

Applying $\left\langle v_{\ell, j} \otimes v_{m, t},-\right\rangle$ to the equality above we get

$$
\begin{aligned}
\left\langle v_{\ell, j} \otimes v_{m, t},[a \otimes 1+1 \otimes a, r]\right\rangle & =\sum_{k \geqslant 0} \sum_{i=1}^{d}\left\langle v_{\ell, j} \otimes v_{m, t},\left(v_{k, i} \otimes 1\right) \delta(a) \otimes \varepsilon_{k, i}\right\rangle \\
& =\left\langle v_{\ell, j},\left(v_{m, t} \otimes 1\right) \delta(a)\right\rangle \\
& =\left\langle v_{\ell, j} \otimes v_{m, t},-\delta(a)\right\rangle
\end{aligned}
$$

Applying instead $\left\langle\varepsilon_{\ell, j} \otimes v_{m, t},-\right\rangle$ to the same equality we obtain

$$
\begin{aligned}
\left\langle\varepsilon_{\ell, j} \otimes v_{m, t},[a \otimes 1+1 \otimes a, r]\right\rangle & =\sum_{k \geqslant 0} \sum_{i=1}^{d}\left\langle\varepsilon_{\ell, j} \otimes v_{m, t},\left(-v_{k, i} \circ \operatorname{ad}_{a}\right) \otimes \varepsilon_{k, i}+v_{k, i} \otimes\left[a, \varepsilon_{k, i}\right]\right\rangle \\
& =-\left\langle\varepsilon_{\ell, j}, v_{m, t} \circ \operatorname{ad}_{a}\right\rangle+\left\langle v_{m, t},\left[a, \varepsilon_{\ell, j}\right]\right\rangle \\
& =0
\end{aligned}
$$

This implies the desired equality $[a \otimes 1+1 \otimes a, r]=-\delta(a)$. The identity $\mathrm{CYB}(r)=-\varphi$ follows from the skew-symmetry of $r$, Theorem 3.6 and the fact that $\varphi=-\psi$ according to the proof of Lemma 4.2.

Remark 4.5. Assume $r \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket$ is a series such that

$$
\begin{equation*}
[f(x) \otimes 1+1 \otimes f(y), r(x, y)] \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket \tag{36}
\end{equation*}
$$

for all $f \in \mathfrak{g} \llbracket x \rrbracket$. Write $r=s\left(x^{-1}, y\right)+g(x, y)$, where $s \in x^{-1}(\mathfrak{g} \otimes \mathfrak{g})\left[x^{-1}\right\rfloor \llbracket y \rrbracket$ and $g \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$. Then, because of Eq. (36) we must have

$$
\left[a \otimes 1+1 \otimes a, s\left(x^{-1}, y\right)\right]=0
$$

for all $a \in \mathfrak{g}$. Since the $\mathfrak{g}$-invariant elements of $\mathfrak{g} \otimes \mathfrak{g}$ are precisely the multiples of the quadratic Casimir element $\Omega$, we have the identity $s\left(x^{-1}, y\right)=p\left(x^{-1}, y\right) \Omega$ for some $p \in x^{-1} F\left[x^{-1}\right] \llbracket y \rrbracket$. Furthermore, the condition

$$
\left[a x \otimes 1+1 \otimes a y, p\left(x^{-1}, y\right) \Omega\right]=\left[a(x-y) \otimes 1, p\left(x^{-1}, y\right) \Omega\right] \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket
$$

implies $(x-y) p\left(x^{-1}, y\right) \in F \llbracket x, y \rrbracket$, meaning that there exists an $s \in F \llbracket y \rrbracket$ such that $p\left(x^{-1}, y\right)=s(y) /(x-y)$. In other words, $r$ has the form Eq. (20). This result can be considered as another motivation to study series of type ( $n, s$ ).

Observe that if we know one Lagrangian subspace $W_{0}$ inside $L \cong \mathfrak{g} \llbracket x \rrbracket \dot{+} \mathfrak{g} \llbracket x \rrbracket^{\prime}$ then any other Lagrangian subspace can be constructed from $W_{0}$ through twisting. More precisely, if $s=\sum_{i} a_{i} \otimes b^{i} \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$ is a skew-symmetric tensor, then we can associate with it a (twisted) Lagrangian subspace

$$
\begin{equation*}
W_{s}:=\left\{\sum_{i} B\left(b^{i}, w\right) a_{i}-w \mid w \in W\right\} \subseteq L \tag{37}
\end{equation*}
$$

complementary to $\mathfrak{g} \llbracket x \rrbracket$. The converse is also true; for proof see 3 . In other words, the following statement holds.

Lemma 4.6. There is a bijection between Lagrangian subspaces $W \subseteq L(n, \alpha)$ or $L(\infty)$ and skew-symmetric tensors in $(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$.

Combining Proposition 4.4 Eq. (37) and the algorithm for constructing a quasi- $r$-matrix from a Lagrangian subspace $W \subset L(n, \alpha), W+\Delta=L(n, \alpha)$, we obtain the following twisting rules for Lagrangian subspaces, quasi-Lie bialgebra structures and quasi- $r$-matrices.

Lemma 4.7. Let $(\mathfrak{g} \llbracket x \rrbracket, \delta, \varphi)$ be a topological quasi-Lie bialgebra structure corresponding to the quasi-r-matrix $r$. If we twist $W(r)$ with a skew-symmetric tensor $s$ as described in Eq. (37) we obtain another topological quasi-Lie bialgebra $\left(\mathfrak{g} \llbracket x \rrbracket, \delta_{s}, \varphi_{s}\right)$, such that

1. $W(r)_{s}=W(r-s)$;
2. $\delta_{s}=\delta+d s$;
3. $\varphi_{s}=\varphi+\operatorname{CYB}(s)-\frac{1}{2} \operatorname{Alt}((\delta \otimes 1) s)$,
where $d s(a):=[a \otimes 1+1 \otimes a, s]$.
Remark 4.8. Since any quasi- $r$-matrix $r$ defines a topological quasi-Lie bialgebra structure $\delta(a)=[a \otimes 1+1 \otimes a, r]$ on $\mathfrak{g} \llbracket x \rrbracket$, the third condition in Definition 4.1 is trivially satisfied. In other words,

$$
\operatorname{Alt}((\delta \otimes 1 \otimes 1) \mathrm{CYB}(r))=0
$$

for any quasi- $r$-matrix $r$.
Lemma 4.6 and Lemma 4.7 state that, in order to obtain a description of topological quasi-Lie bialgebra structures on $\mathfrak{g} \llbracket x \rrbracket$ up to twisting it is enough to find a single Lagrangian subspace $W_{0}$, complementary to $\mathfrak{g} \llbracket x \rrbracket$, inside $L(\infty)$ and each $L(n, \alpha)$. The same is true for the associated quasi- $r$-matrices

The case $L(\infty)$ is trivial, because by definition $\mathfrak{g} \llbracket x \rrbracket^{\prime}=\bigoplus_{j \geqslant 0} \mathfrak{g} \otimes a_{j} \subseteq L(\infty)$ is a Lagrangian subalgebra (see Definition 2.1. Similar to the Lie bialgebra case, topological quasi-Lie bialgebras corresponding to the Manin pair $(L(\infty), \mathfrak{g} \llbracket x \rrbracket)$ are called degenerate.

Let us now focus on non-degenerate topological quasi-Lie bialgebra structures, i.e. the ones corresponding to the Manin pairs $(L(n, \alpha), \Delta)$. By Proposition 2.5 for each Manin pair $(L(n, \alpha), \Delta)$ there exists an appropriate coordinate transformation that makes it into $(L(n, \beta), \Delta)$, where $\beta_{0}=\alpha_{0}$ and all other $\beta_{i}=0$. This means, that to classify all non-degenerate topological quasi-Lie bialgebras on $\mathfrak{g} \llbracket x \rrbracket$, up to coordinate transformations and twisting, it is enough to construct a Lagrangian subspace $W_{0}$ within each $L\left(n, \alpha_{0}\right):=L\left(n,\left(\ldots, 0, \alpha_{0}, 0, \ldots, 0\right)\right)$ complementary to $\Delta$. Equivalently, it is enough to find a quasi- $r$-matrix of type ( $n, \alpha_{0}$ ) for any $n \geqslant 0$ and $\alpha_{0} \in F$.

### 4.1 Lagrangian subspaces of $L\left(n, \alpha_{0}\right)$

As before we let $\left\{b_{i}\right\}_{i=1}^{d}$ be an orthonormal basis for $\mathfrak{g}$ with respect to the Killing form $\kappa$. The form $B$ on $L\left(n, \alpha_{0}\right)$ has the following explicit form

$$
B(a \otimes(f,[p]), b \otimes(g,[q]))= \begin{cases}\kappa(a, b)\left\{\operatorname{coeff}_{n-1}(f g-p q)-\alpha_{0} \operatorname{coeff}_{0}(f g-p q)\right\} & \text { if } n \geqslant 2  \tag{38}\\ \kappa(a, b) \operatorname{coeff}_{n-1}(f g-p q) & \text { if } n=0,1\end{cases}
$$

We now present an explicit construction for a Lagrangian subspace of $L\left(n, \alpha_{0}\right)$ complementary to $\Delta$ for arbitrary $n \geqslant 0$ and $\alpha_{0} \in F$. Using the twisting procedure from Lemma 4.7, this subspace can be twisted in order to obtain all other Lagrangian subspaces of $L\left(n, \alpha_{0}\right)$ complementary to $\Delta$.
$\mathbf{n}=\mathbf{0}: \quad$ When $n=0$, the subalgebra $W_{0}:=x^{-1} \mathfrak{g} \llbracket x^{-1} \rrbracket \subseteq \mathfrak{g}((x))$ is known to be Lagrangian.
$\mathbf{n}=\mathbf{1}$ : For $n=1$ it is easy to see that the subspace

$$
\begin{equation*}
W_{0}:=\operatorname{span}_{F}\left\{b_{i}(1,-1), b_{i}\left(x^{-k}, 0\right) \mid k \geqslant 1,1 \leqslant i \leqslant d\right\} \subset L\left(1, \alpha_{0}\right) \tag{39}
\end{equation*}
$$

is Lagrangian and complementary to the diagonal $\Delta$.
$\mathbf{n}=\mathbf{2 k}$ : For even $n \geqslant 2$ and arbitrary $\alpha_{0} \in F$ the subspace $W_{0} \subset L\left(n, \alpha_{0}\right)$ spanned by the elements

$$
\begin{aligned}
& b_{i}\left\{\left(x^{(n-1)-m}, 0\right)-\alpha_{0}\left(x^{2(n-1)-m}, 0\right)+\alpha_{0}^{2}\left(x^{3(n-1)-m}, 0\right)-\alpha_{0}^{3}\left(x^{4(n-1)-m}, 0\right)+\ldots\right\}, 0 \leqslant m \leqslant \frac{n}{2}-1 \\
& b_{i}\left(0,-[x]^{(n-1)-\ell}\right), \frac{n}{2} \leqslant \ell<n-1 \\
& b_{i}\left(0,-1+\frac{\alpha_{0}}{2}[x]^{n-1}\right) \\
& b_{i}\left(x^{-k}, 0\right), k \geqslant 1
\end{aligned}
$$

is Lagrangian and complementary to the diagonal.
$\mathbf{n}=\mathbf{2 k}+\mathbf{1}: \quad$ Modifying slightly the basis for even case we obtain the following basis for $W_{0} \subset L\left(n, \alpha_{0}\right)$ with odd $n \geqslant 3$ :

$$
\begin{aligned}
& b_{i}\left\{\left(x^{(n-1)-m}, 0\right)-\alpha_{0}\left(x^{2(n-1)-m}, 0\right)+\alpha_{0}^{2}\left(x^{3(n-1)-m}, 0\right)-\alpha_{0}^{3}\left(x^{4(n-1)-m}, 0\right)+\ldots\right\}, 0 \leqslant m \leqslant \frac{n-1}{2}-1, \\
& b_{i}\left\{\left(x^{\frac{n-1}{2}},-[x]^{\frac{n-1}{2}}\right)-\alpha_{0}\left(x^{\frac{3(n-1)}{2}}, 0\right)+\alpha_{0}^{2}\left(x^{\frac{5(n-1)}{2}}, 0\right)-\alpha_{0}^{3}\left(x^{\frac{7(n-1)}{2}}, 0\right)+\ldots\right\}, \\
& b_{i}\left(0,-[x]^{(n-1)-\ell}\right), \frac{n-1}{2}+1 \leqslant \ell<n-1, \\
& b_{i}\left(0,-1+\frac{\alpha_{0}}{2}[x]^{n-1}\right), \\
& b_{i}\left(x^{-k}, 0\right), k \geqslant 1 .
\end{aligned}
$$

The subspaces above were constructed by "guessing". However, there is an abstract procedure that produces Lagrangian subspaces for arbitrary $n$ and $\alpha$. We present it here for completeness.

The easiest skew-symmetric $(n, s)$-type series is given by

$$
\begin{aligned}
r(x, y) & :=\frac{1}{2}\left(\frac{s(x) y^{n} \Omega}{x-y}+\frac{s(y) x^{n} \Omega}{x-y}\right)=\frac{s(x) y^{n} \Omega}{x-y}+\frac{\Omega}{2}\left(\frac{s(y) x^{n}-s(x) y^{n}}{x-y}\right) \\
& =\frac{s(x) y^{n} \Omega}{x-y}-\frac{1}{2} \sum_{k, \ell=0}^{\infty} \sum_{i, j=1}^{d} B\left(s w_{k, i}, s w_{\ell, j}\right) b_{i}(x,[x])^{k} \otimes b_{j}(y,[y])^{\ell},
\end{aligned}
$$

where we recall that

$$
B\left(s w_{k, i}, s w_{\ell, j}\right)= \begin{cases}-s_{k+\ell-n+1} & \text { if } i=j, 0 \leqslant k, \ell \leqslant n-1 \text { and } k+\ell \geqslant n-1, \\ s_{k+\ell-n+1} & \text { if } i=j \text { and } k, \ell \geqslant n, \\ 0 & \text { otherwise } .\end{cases}
$$

By Corollary 3.7 the subspace

$$
\begin{aligned}
W(r) & =\operatorname{span}_{F}\left\{\left.s w_{k, i}-\frac{1}{2} \sum_{\ell=0}^{\infty} B\left(s w_{\ell, i}, s w_{k, i}\right) b_{i}(x,[x])^{\ell} \right\rvert\, k \geqslant 0,1 \leqslant d \leqslant n\right\} \\
& =\operatorname{span}_{F}\left\{\left.s w_{k, i}+\frac{1}{2}\left(\sum_{\ell=0}^{n-1} s_{k+\ell-n+1} b_{i}(x,[x])^{\ell}-\sum_{\ell=n}^{\infty} s_{k+\ell-n+1} b_{i}(x,[x])^{\ell}\right) \right\rvert\, k \geqslant 0,1 \leqslant d \leqslant n\right\}
\end{aligned}
$$

is Lagrangian and complementary to the diagonal. Here we used the convention that $s_{k}=0$ for $k<0$. Calculating the basis explicitly for some particular $s$ requires some effort and it may not look as friendly as the ones given above.

### 4.2 Quasi- $r$-matrices

The goal of this section is to describe the quasi- $r$-matrices corresponding to the Lagrangian subspaces described in the previous section. The twisting procedure from Lemma 4.7 then yields all other quasi- $r$-matrices.

The proof of Theorem 3.6 gives us an algorithm for constructing a series of type ( $n, s(x):=1 /\left(x^{n} \alpha(x)\right)$ ) from a subspace $W \subset L(n, \alpha)$ complementary to the diagonal. More precisely, the desired series is given by

$$
\begin{equation*}
\sum_{k \geqslant 0} \sum_{i=1}^{d} v_{k, i} \otimes b_{i}\left(y^{k},[y]^{k}\right), \tag{40}
\end{equation*}
$$

where

$$
W=\operatorname{span}_{F}\left\{v_{k, i} \mid k \geqslant 0,1 \leqslant i \leqslant d\right\} \text { and } B\left(v_{k, i}, b_{j}\left(y^{\ell},[y]^{\ell}\right)\right)=\delta_{i, j} \delta_{k, \ell},
$$

i.e. $\left\{v_{k, i}\right\}$ is a basis of $V$ dual to $\left\{b_{i}\left(y^{k},[y]^{k}\right)\right\}$. Indeed, non-degeneracy of the form $B$ then implies that $v_{k, i}$ has the desired form $v_{k, i}=s w_{k, i}+g_{k, i}$ for some $g_{k, i} \in(\mathfrak{g} \otimes \mathfrak{g}) \llbracket x, y \rrbracket$.

Applying this idea to $W_{0}$ 's constructed in the preceding section we get the following series.
$\mathbf{n}=\mathbf{0}$ : The classical $r$-matrix (equivalently ( 0,1 )-type series) corresponding to $W_{0}:=x^{-1} \mathfrak{g} \llbracket x^{-1} \rrbracket \subseteq \mathfrak{g}((x))$ is the Yang's matrix $\Omega /(x-y)$.
$\mathbf{n}=1: \quad$ The quasi- $r$-matrix corresponding $\operatorname{to~}_{\operatorname{span}}^{F}\left\{b_{i}(1,-1), b_{i}\left(x^{-k}, 0\right) \mid k \geqslant 1,1 \leqslant i \leqslant d\right\} \subset L\left(1, \alpha_{0}\right)$ is

$$
\frac{y \Omega}{x-y}+\frac{1}{2} \sum_{i=1}^{d} b_{i}(1,-1) \otimes b_{i}(1,1) \in L_{2}(1,1) \text { with the projection } \frac{y \Omega}{x-y}+\frac{1}{2} \Omega \in(\mathfrak{g} \otimes \mathfrak{g})((x)) \llbracket y \rrbracket .
$$

$\mathbf{n}=\mathbf{2 k}$ : For even $n \geqslant 2$ and arbitrary $\alpha_{0} \in F$ we have the following quasi- $r$-matrix

$$
\begin{aligned}
\frac{1}{1+\alpha_{0} x^{n-1}} \frac{y^{n} \Omega}{x-y} & +\frac{\Omega}{1+\alpha_{0} x^{n-1}} \sum_{0 \leqslant m<\frac{n}{2}} x^{(n-1)-m} y^{m} \\
& +\frac{\alpha_{0} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)}\left(y^{2(n-1)}+\sum_{\frac{n}{2} \leqslant \ell<n-1} x^{(n-1)-\ell} y^{(n-1)+\ell}-\frac{1}{2} x^{n-1} y^{n-1}\right) .
\end{aligned}
$$

$\mathbf{n}=\mathbf{2 k}+\mathbf{1}: \quad$ In the odd case $n \geqslant 3$ the series corresponding to $W_{0} \subset L\left(n, \alpha_{0}\right)$ is

$$
\begin{aligned}
\frac{1}{1+\alpha_{0} x^{n-1}} \frac{y^{n} \Omega}{x-y} & +\frac{\Omega}{1+\alpha_{0} x^{n-1}}\left(x^{\frac{n-1}{2}} y^{\frac{n-1}{2}}+\sum_{0 \leqslant m<\frac{n-1}{2}} x^{(n-1)-m} y^{m}\right) \\
& +\frac{\alpha_{0} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)}\left(y^{2(n-1)}+\sum_{\frac{n-1}{2}<\ell<n-1} x^{(n-1)-\ell} y^{(n-1)+\ell}-\frac{1}{2} x^{n-1} y^{n-1}\right) .
\end{aligned}
$$

## 5 Lie algebra splittings of $L(n, \alpha)$ and generalized $r$-matrices

By Corollary 3.7 we have a bijection between subalgebras of $L(n, \alpha)$ and series of type ( $n, 1 /\left(x^{n} \alpha(x)\right)$ ) solving GCYBE. Therefore, we can construct new solutions to GCYBE by finding subalgebras of $L(n, \alpha)$ complementary to the diagonal. However, as the following result shows, the most interesting new solutions should arise from unbounded subalgebras of $L(n, \alpha), n>2$.

Proposition 5.1. Let $L(n, \alpha)=\Delta \dot{+} W$ for some subalgebra $W \subset L(n, \alpha)$ and $n>2$. Assume $W$ is bounded, i.e. there is an integer $N>0$ such that

$$
x^{-N} \mathfrak{g}\left[x^{-1}\right] \subseteq W_{+} \subseteq x^{N} \mathfrak{g}\left[x^{-1}\right]
$$

where $W_{+}$is the projection of $W \subset L(n, \alpha)=\mathfrak{g}((x)) \oplus \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]$ on the first component $\mathfrak{g}((x))$. Then there is an element $\sigma \in \operatorname{Aut}_{F[x]-\operatorname{LieAlg}}(\mathfrak{g}[x])$ such that

$$
\{0\} \times\left[x^{2}\right] \mathfrak{g}[x] / x^{n} \mathfrak{g}[x] \subseteq(\sigma \times \sigma) W \subseteq x \mathfrak{g}\left[x^{-1}\right] \times \mathfrak{g}[x] / x^{n} \mathfrak{g}[x]
$$

and the image $\widetilde{W}$ under the canonical projection $L(n, \alpha) \rightarrow L(2, \alpha)$ is a subalgebra satisfying $L(2, \alpha)=\Delta \dot{+} \widetilde{W}$.
In the language of $(n, s)$-type series: Let

$$
r=\frac{s(x) y^{n} \Omega}{x-y}+g(x, y)
$$

be the generalized $r$-matrix corresponding to a bounded $W \subset L(n, \alpha), n \geqslant 2$. Then there is $p(x, y) \in(\mathfrak{g} \otimes \mathfrak{g})[x, y]$ of degree at most one in $x$ and an element $\sigma \in \operatorname{Aut}_{F[x]-\operatorname{LieAlg}}(\mathfrak{g}[x])$ such that

$$
(\sigma(x) \otimes \sigma(y)) r(x, y)=y^{n-2}(\underbrace{\frac{s(x) y^{2} \Omega}{x-y}+p(x, y)}_{r^{\prime}(x, y)}),
$$

where $r^{\prime}$ is a generalized $r$-matrix in $L_{2}(2, \alpha)$.
Proof. The condition $x^{-N} \mathfrak{g}\left[x^{-1}\right] \subseteq W_{+} \subseteq x^{N} \mathfrak{g}\left[x^{-1}\right]$ means exactly that $W_{+}$is an order. Moreover, since $W$ is complementary to the diagonal, we have $W_{+}+\mathfrak{g}[x]=\mathfrak{g}\left[x, x^{-1}\right]$. It was shown in 11 that such orders, up to the action of some $\sigma \in \operatorname{Aut}_{F[x]-\operatorname{LieAlg}}(\mathfrak{g}[x])$, are contained in a maximal order $\mathfrak{M}$ associated to the so called fundamental simplex $\Delta_{\text {st }}$. These maximal orders are explicitly described in 11 and satisfy $\mathfrak{M} \subseteq x \mathfrak{g}\left[x^{-1}\right]$. Therefore, we have $\sigma W_{+} \subseteq \mathfrak{M} \subseteq x \mathfrak{g}\left[x^{-1}\right]$. Moreover, we have the identity

$$
(\sigma \times \sigma) W \dot{+} \Delta=L(n, \alpha)
$$

implying the inclusion $\{0\} \times\left[x^{2}\right] \mathfrak{g}[x] / x^{n} \mathfrak{g}[x] \subseteq(\sigma \times \sigma) W$. The remaining parts follow straightforward from the construction Theorem 3.6

Unfortunately, we have not found a new example of an unbounded subalgebra of $L(n, \alpha)$. However, we present an infinite family of bounded subalgebras. We believe these examples are still interesting because their orthogonal complements, which are important in the view of Adler-Kostant-Symes scheme, are unbounded if $\alpha \neq 0$.

Consider the subspaces of $L\left(n, \alpha_{0}\right), n>0$ :

$$
\begin{aligned}
& W_{0}=\operatorname{span}_{F}\left\{b_{i}\left(x^{-k}, 0\right), b_{i}(1,0), b_{i}\left(0,-[x]^{\ell}\right) \mid k \geqslant 1,1 \leqslant \ell \leqslant n-1\right\} \\
& W_{1}=\operatorname{span}_{F}\left\{b_{i}\left(x^{-k}, 0\right), b_{i}(0,-1), b_{i}\left(0,-[x]^{\ell}\right) \mid k \geqslant 1,1 \leqslant \ell \leqslant n-1\right\}
\end{aligned}
$$

These are clearly subalgebras. The corresponding generalizerd $r$-matrices are

$$
\begin{aligned}
r_{0}= & \frac{1}{1+\alpha_{0} x^{n-1}} \frac{y^{n} \Omega}{x-y}+\frac{y^{n-1} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)} \\
& +\frac{\alpha_{0} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)}\left(y^{2(n-1)}+\sum_{0 \leqslant \ell<n-1} x^{(n-1)-\ell} y^{(n-1)+\ell}\right) \\
= & \frac{y^{n-1}}{1+\alpha_{0} y^{n-1}}\left(\frac{y \Omega}{x-y}+\Omega\right), \\
r_{1}= & \frac{1}{1+\alpha_{0} x^{n-1}} \frac{y^{n} \Omega}{x-y}+\frac{\alpha_{0} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)}\left(y^{2(n-1)}+\sum_{0<\ell<n-1} x^{(n-1)-\ell} y^{(n-1)+\ell}\right) \\
= & \frac{1}{1+\alpha_{0} y^{n-1}} \frac{y^{n} \Omega}{x-y} .
\end{aligned}
$$

By considering decompositions $\mathfrak{g}=\mathfrak{s}_{1}+\mathfrak{s}_{2}$ of $\mathfrak{g}$ into direct sums of subalgebras we can get an infinite family of generalized $r$-matrices "in between" $r_{0}$ and $r_{1}$. More precisely, let $\left\{s_{1, i}\right\}_{i=1}^{d_{1}}$ and $\left\{s_{2, j}\right\}_{j=1}^{d_{2}}$ be bases for $\mathfrak{s}_{1}$ and $\mathfrak{s}_{2}$ respectively. Such a decomposition leads to another subalgera of $L\left(n, \alpha_{0}\right)$ :

$$
\begin{array}{r}
W_{01}:=\operatorname{span}_{F}\left\{b_{i}\left(x^{-k}, 0\right), s_{1, m}(1,0), s_{2, j}(0,1), b_{i}\left(0,-[x]^{\ell}\right) \mid k \geqslant 1,1 \leqslant \ell \leqslant n-1,1 \leqslant i \leqslant d\right. \\
\left.1 \leqslant m \leqslant d_{1}, 1 \leqslant j \leqslant d_{2}\right\} .
\end{array}
$$

Rewrite the elements $b_{i}$ in terms of $s_{1, m}$ and $s_{2, j}$ :

$$
b_{i}=\sum_{m=1}^{d_{1}} \lambda_{1, m}^{i} s_{1, m}+\sum_{j=1}^{d_{2}} \lambda_{2, j}^{i} s_{2, j}
$$

where $\lambda_{1, m}^{i}, \lambda_{2, j}^{i} \in F$. Finding a basis in $W_{12}$ dual to $\left\{b_{i}\left(y^{m},[y]^{m}\right)\right\} \subset \Delta$ and then projecting the generating series for $W_{01}$ onto the first component we obtain the following generalized $r$-matrix

$$
\begin{align*}
r_{01} & =\frac{1}{1+\alpha_{0} x^{n-1}} \frac{y^{n} \Omega}{x-y}+\frac{\alpha_{0} \Omega}{\left(1+\alpha_{0} x^{n-1}\right)\left(1+\alpha_{0} y^{n-1}\right)}\left(y^{2(n-1)}+\sum_{0<\ell<n-1} x^{(n-1)-\ell} y^{(n-1)+\ell}\right) \\
& +\frac{y^{n-1}}{1+\alpha_{0} y^{n-1}} \sum_{i=1}^{d} \sum_{m=1}^{d_{1}} \lambda_{1, m}^{i} s_{1, m} \otimes b_{i} .  \tag{41}\\
& =\frac{y^{n-1}}{1+\alpha_{0} y^{n-1}}\left(\frac{y \Omega}{x-y}+\sum_{i=1}^{d} \sum_{m=1}^{d_{1}} \lambda_{1, m}^{i} s_{1, m} \otimes b_{i}\right)
\end{align*}
$$

Clearly $r_{01}$ coincides with $r_{0}$ when $\mathfrak{s}_{1}=\mathfrak{g}$ and $r_{1}$ if $\mathfrak{s}_{2}=\mathfrak{g}$. The corresponding orhogonal complements are

$$
\begin{align*}
& W_{0}^{\perp}=W\left(\overline{r_{0}}\right)=\operatorname{span}_{F}\left\{b_{i}\left(0,[x]^{n-1}\right), \left.b_{i}\left(\frac{x^{-k(n-1)-m}}{1+\alpha_{0} x^{n-1}}, 0\right) \right\rvert\, k \geqslant-1,0<m<n-1\right\}, \\
& W_{1}^{\perp}=W\left(\overline{r_{1}}\right)=\operatorname{span}_{F}\left\{\left.b_{i}\left(\frac{x^{-k(n-1)-m}}{1+\alpha_{0} x^{n-1}}, 0\right) \right\rvert\, k \geqslant-1,0 \leqslant m<n-1\right\},  \tag{42}\\
& \begin{aligned}
W_{01}^{\perp}=W\left(\overline{r_{01}}\right)=\mathfrak{s}_{1}^{\perp} & \left(\frac{x^{n-1}}{1+\alpha_{0} x^{n-1}}, 0\right)+\mathfrak{s}_{2}^{\perp}\left(0,[x]^{n-1}\right) \\
& \quad+\operatorname{span}_{F}\left\{\left.b_{i}\left(\frac{x^{-k(n-1)-m}}{1+\alpha_{0} x^{n-1}}, 0\right) \right\rvert\, k \geqslant-1,0<m<n-1\right\},
\end{aligned}
\end{align*}
$$

which are unbounded because of the factor $1 /\left(1+\alpha_{0} x^{n-1}\right)$.
Note that a series of type $(n, s)$ defines a subspace inside $L(n, \alpha)$ for any $\alpha$, because the subalgebra property is not affected by the form. With the previous examples in mind we can prove the following statement.

Lemma 5.2. Let $B_{0}$ and $B_{\alpha}$ be the bilinear forms on $L(n, 0)$ and $L(n, \alpha)$ respectively. For a series $r$ of type $(n, s)$ we have

$$
\begin{equation*}
W(r)^{\perp_{B_{\alpha}}}=\frac{1}{x^{n} \alpha(x)} W(r)^{\perp_{B_{0}}} \subset L(n, \alpha) \tag{43}
\end{equation*}
$$

Proof. Set $u(x):=1 /\left(x^{n} \alpha(x)\right)$. Write

$$
r=\sum_{k \geqslant 0} \sum_{i=1}^{d}\left(s w_{k, i}+g_{k, i}\right) \otimes b_{i}\left(y^{k},[y]^{k}\right) \text { and } \bar{r}=\sum_{k \geqslant 0} \sum_{i=1}^{d}\left(s w_{k, i}+\overline{g_{k, i}}\right) \otimes b_{i}\left(y^{k},[y]^{k}\right) .
$$

Then by Theorem 3.6 and definition Eq. (11) $B_{\alpha}\left(s w_{k, i}+g_{k, i}, u\left(s w_{\ell, j}+\overline{g_{\ell, j}}\right)\right)=B_{0}\left(s w_{k, i}+g_{k, i}, s w_{\ell, j}+\overline{g_{\ell, j}}\right)=0$

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## Data availability statements

Data sharing not applicable to this article as no datasets were generated or analysed during the current study.

## Declarations

The authors have no competing interests to declare that are relevant to the content of this article.

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